

Classical Mechanics (Numerical Simulation)

- Collision in two dimensions
- Harmonic oscillator (+ damped oscillator, forced oscillator)

$$\frac{d^2}{dt^2}x = -2\zeta\frac{d}{dt}x - kx + f\sin\omega t \quad (m=1)$$

- Coupling of two linear oscillators 1
- Coupling of two linear oscillators 2

$$\begin{array}{l} m_1\frac{d^2}{dt^2}x_1 = -k_1x_1 + k'\left(x_2 - x_1\right) \\ m_2\frac{d^2}{dt^2}x_2 = -k_2x_2 - k'\left(x_2 - x_1\right) \end{array}$$

- Motion in the potential U(x) (+ damping)

$$\begin{array}{l} m\frac{d^2}{dt^2}x = -\mu\frac{d}{dt}x - \frac{dU}{dx} \\ U(x) = -\frac{1}{2}x^2 + \frac{1}{4}x^4 \end{array}$$

- Parabolic motion (+ viscous resistance, inertial resistance)

$$\begin{array}{l} \frac{d}{dt}\vec{r} = \vec{v} \\ m\frac{d}{dt}\vec{v} = -m\vec{g} - \gamma_1\vec{v} - \gamma_2|\vec{v}|\vec{v} \end{array}$$

- Monkey Hunting
- Satellite orbits around a planet 1 (, where the planet is fixed)

$$\frac{d^2}{dt^2}\vec{r} = -G\frac{Mm}{r^2}\frac{\vec{r}}{r}$$

- Satellite orbits around a planet 2 (, where the planet can move)
- Swing-by Motion

- Wave Motion

$$\rho\frac{\partial^2}{\partial t^2}u = T\frac{\partial^2}{\partial x^2}u$$

- Rutherford Scattering
- Single Pendulum Motion

$$\frac{d^2}{dt^2}\theta = -\frac{g}{\ell}\sin\theta$$

- Double Pendulum Motion 1
- Double Pendulum Motion 2 (+ time sequence and phase space)

$$\frac{d}{dt}\left(\begin{array}{c} \theta_1 \\ \theta_2 \end{array}\right) = \left(\begin{array}{c} \omega_1 \\ \omega_2 \end{array}\right)$$

$$\frac{d}{dt} \left(\begin{array}{c} \omega_1 \\ \omega_2 \end{array} \right) = \sin(\theta_1 - \theta_2) A^{-1} \left(\begin{array}{c} -\mu \alpha \omega_2^2 \\ \omega_1^2 \end{array} \right) - A^{-1} \left(\begin{array}{c} \sin \theta_1 \\ \sin \theta_2 \end{array} \right)$$

$$A^{-1} = \frac{1}{\alpha \{ 1 - \mu \cos^2(\theta_1 - \theta_2) \}} \left(\begin{array}{cc} \alpha & -\mu \alpha \cos(\theta_1 - \theta_2) \\ -\cos(\theta_1 - \theta_2) & 1 \end{array} \right)$$
